

LAMPIRAN

Lampiran 1 Listing Program Aliran Daya Pada Sistem IEEE 30 Bus Setelah Penempatan STATCOM Dengan Optimasi BFO

```
clc;
clear;
basemva = 100; accuracy = 10^-8; accel = 1.8; maxiter = 1000;
% Bus Data IEEE30
% Line Data IEEE30
%% Bacterial Foraging Optimization
Nvar =3; % Jumlah STATCOM
NBac = 20; % Number of bacteria in the colony
NChem = 10; % Number of chemotactic steps
NSwim = 4; % Number of swim steps
NRep = 10; % Number of reproductive steps
NEDi = 10; % Number of elimination and dispersal steps
Sr = NBac/2; % The number of bacteria reproductions (splits) per
generation
PEDI = 0.5; % The probability that each bacteria will be
eliminated/dispersed
RLeng(:,1)=25*ones(NBac,1); % the run length unit (the size of the step
taken in each run or tumble)
Rb1 = 1; % Batas bawah interval Lokasi
Ra1 = max(busdata(:,1)); % Batas akhir interval Lokasi
Rb2 =-5; % Batas bawah interval MVAR
Ra2 =100; % Batas atas interval MVAR

% the initital posistions
for nn = 1 : NBac
    X1(:,nn,1,1,1) = randperm(Ra1,Nvar);
    X2(:, :,1,1,1) = ((rand(NBac,Nvar)*(Ra2-Rb2))+Rb2)';
end

for lll = 1:NEDi
    % (3) Reproduction loop
    for kkk = 1:NRep
        % (4) Chemotaxis (swim/tumble) loop
        for jjj = 1:NChem
            % (4.1) Chemotatic step
            for iii = 1:NBac
                % (4.2) Fitness function
                Fit(iii,jjj,kkk,lll) =
                EvaluasiIndividu(busdata,linedata,X1(:,iii,jjj,kkk,lll),X2(:,iii,jjj,kkk,
                lll),Nvar);
                % (4.3) Jlast
                Fitlast=Fit(iii,jjj,kkk,lll);
                % (4.4) Tumble
                Delta(:,iii) = unifrnd(-1,1,Nvar,1);
                % (4.5) Move
                X1(:,iii,jjj+1,kkk,lll)= randperm(Ra1,Nvar);
                X2(:,iii,jjj+1,kkk,lll)=
                X2(:,iii,jjj,kkk,lll)+RLeng(iii,kkk)*Delta(:,iii)/sqrt(Delta(:,iii) '*Delt
                a(:,iii));
                for chck=1:Nvar
                    if X2(chck,iii,jjj+1,kkk,lll) > Ra2
                        X2(chck,iii,jjj+1,kkk,lll) = Ra2;
                    elseif X2(chck,iii,jjj+1,kkk,lll) < Rb2
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        X2(chck,iii,jjj+1,kkk,111) = Rb2;
    end
end
% (4.6) New fitness function
Fit(iii,jjj+1,kkk,111) =
EvaluasiIndividu(busdata,linedata,X1(:,iii,jjj+1,kkk,111),X2(:,iii,jjj+1,
kkk,111),Nvar);
% (4.7) Swimming
m=0; % counter for swim length
while m < NSwim
    m = m + 1;
    if Fit(iii,jjj+1,kkk,111) > Fitlast
        Fitlast = Fit(iii,jjj+1,kkk,111);
        X1(:,iii,jjj+1,kkk,111) = randperm(Ra1,Nvar);
        X2(:,iii,jjj+1,kkk,111) =
X2(:,iii,jjj+1,kkk,111)+RLeng(iii,kkk)*Delta(:,iii)/sqrt(Delta(:,iii)'*De
lta(:,iii));

        for chck=1:Nvar
            if X2(chck,iii,jjj+1,kkk,111) > Ra2
                X2(chck,iii,jjj+1,kkk,111) = Ra2;
            elseif X2(chck,iii,jjj+1,kkk,111) < Rb2
                X2(chck,iii,jjj+1,kkk,111) = Rb2;
            end
        end
        Fit(iii,jjj+1,kkk,111) =
EvaluasiIndividu(busdata,linedata,X1(:,iii,jjj+1,kkk,111),X2(:,iii,jjj+1,
kkk,111),Nvar);
    else
        m = NSwim;
    end
end
Fit(iii,jjj,kkk,111) = Fitlast;
end % (4.8) Next bacterium
end % (5) if j < Nc, chemotaxis
% (6) Reproduction
% (6.1) Health
Fithealth = sum(Fit(:, :, kkk, 111), 2); % Set the health of
each of the S bacteria
[Fithealth, sortind] = sort(Fithealth, 'descend'); % Sorts bacteria
in order of descending values
X1(:, :, 1, kkk+1, 111) = X1(:, sortind, NChem+1, kkk, 111);
X2(:, :, 1, kkk+1, 111) = X2(:, sortind, NChem+1, kkk, 111);
RLeng(:, kkk+1) = RLeng(sortind, kkk); % Keeps the
chemotaxis parameters with each bacterium at the next generation
% (6.2) Split the bacteria
for spl=1:Sr % Sr??
    X1(:, spl+Sr, 1, kkk+1, 111) = X1(:, spl, 1, kkk+1, 111); % The
least fit do not reproduce, the most fit ones split into two identical
copies
    X2(:, spl+Sr, 1, kkk+1, 111) = X2(:, spl, 1, kkk+1, 111);
    RLeng(spl+Sr, kkk+1) = RLeng(spl, kkk+1);
end
end % (7) Loop to go to the next reproductive step
% (8) Elimination-dispersal
for mmm = 1:NBac
    if PEDi > rand % % Generate random number
        X1(:, mmm, 1, 1, 111+1) = randperm(Ra1, Nvar);
        X2(:, mmm, 1, 1, 111+1) = ((rand(1, Nvar) * (Ra2 - Rb2)) + Rb2)';
    else
        X1(:, mmm, 1, 1, 111+1) = X1(:, mmm, 1, NRep+1, 111); % Bacteria that
are not dispersed
    end
end

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X2(:,mmm,1,1,1ll+1)=X2(:,mmm,1,NRep+1,1ll);
end
end
end
reproduction = Fit(:,1:NChem,NRep,NEDi);
[bc,abc]=max(reproduction,[],2);
[~,man]=max(bc);
BestX2=X2(:,man,abc(man,:),kkk,1ll);
BestX1=X1(:,man,abc(man,:),kkk,1ll);

for i=1:Nvar
    if busdata(BestX1(i),2)==0
        busdata(BestX1(i),11) = BestX2(i);
    end
end
end

```

Lampiran 2 Listing Program Aliran Daya Metode *Newton Raphson* Pada Sistem JAMALI 500kV Tanpa STATCOM

```

clear
clc
format long
tic
basemva = 1000; accuracy = 10^-4; accel = 1.8; maxiter = 100;
% Bus Data jamali 500kV

```

Bus No	Bus Code	Voltage Magnitude	Angle Degree	Load MW	Load MVAR	Generator MW	Generator MVAR	
1	1	1.020	0	147.86	77.44	2766	1144	%suralaya
2	0	1.000	0	100.23	193.24	0	0	%cilegon
3	0	1.000	0	122	144	0	0	%kembangan
4	0	1.000	0	571.28	-31.2	0	0	%Gandul
5	0	1.000	0	367.32	231.14	0	0	%cibinong
6	0	1.000	0	523	108	0	0	%cawang
7	0	1.000	0	740	-7	0	0	%Bekasi
8	2	1.000	0	0	0	767	244.4	%Muaratawar
9	0	1.000	0	947	410	0	0	%cibatu
10	2	1.000	0	667.07	261.07	422	141	%cirata
11	2	1.025	0	0	0	566.93	111.71	%saguling
12	0	1.000	0	557	261	0	0	%bandungsltn
13	0	1.000	0	67.96	66.79	0	0	%mandiracan
14	0	1.000	0	654	410	0	0	%ungaran
15	2	1.000	0	292	55	2230	201	%tanjungjati
16	0	1.000	0	932.85	339.71	0	0	%surabayabrt
17	2	1.000	0	102.3	118.77	515.16	157.34	%gresik
18	0	1.000	0	503.99	108.38	0	0	%depok
19	0	1.000	0	285	92	0	0	%tasikmalaya
20	0	1.000	0	674	231	0	0	%pedan
21	0	1.000	0	615.4345	178.8	0	0	%kediri
22	2	1.000	0	869	210	4038.1	715.060	%Paiton
23	2	1.025	0	447.4	280.3	764	100.05	%grati
24	0	1.000	0	574	164	0	0	%ngimbang
25	0	1.000	0	577	184	0	0	%balaraja
26	0	1.000	0	25.73	4.18	0	0];%ujungberung

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% Line Data JAMALI 500 kV

```

Bus nl	Bus nr	R pu	X pu	1/2 B pu	Tap Setting
1	2	0.000626496	0.007008768	0.0011414290	1
1	25	0.003677677	0.035333317	0.0002264160	1
2	5	0.013133324	0.146925792	0.0000544495	1

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3      4      0.001513179    0.016928308    0.0004726210    1
4      18     0.000694176    0.006669298    0.0023990310    1
5      7      0.00444188     0.0426754     0.0001874620    1
5      8      0.0062116     0.059678     0.0001340530    1
5      11     0.00411138     0.04599504    0.0001739310    1
6      7      0.001973648     0.01896184    0.0004219000    1
6      8      0.0056256     0.054048     0.0001480170    1
8      9      0.002822059     0.027112954    0.0002950630    1
9      10     0.00273996     0.026324191    0.0003055450    1
10     11     0.001474728     0.014168458    0.0005646350    1
11     12     0.0019578     0.0219024     0.0003652570    1
12     13     0.00699098     0.0671659     0.0001191080    1
12     26     0.000385     0.003703     0             1
13     14     0.013478     0.12949     0.0000617810    1
13     26     0.000868     0.0097008     0             1
14     15     0.01353392     0.15140736    0.0001056750    1
14     16     0.01579856     0.1517848     0.0000279497    1
14     20     0.00903612     0.0868146     0.0000921505    1
16     17     0.00139468     0.0133994     0.0005945430    1
16     23     0.003986382     0.044596656    0.0001793860    1
18     5      0.000818994     0.00786848     0.0009126260    1
18     19     0.014056     0.15724802    0.0000508750    1
19     20     0.015311     0.0171288     0.0000467055    1
20     21     0.010291     0.0115128     0.0000694880    1
21     22     0.010291     0.0115128     0.0000694880    1
22     23     0.004435823     0.049624661    0.0001695470    1
24     14     0.023479613     0.225580588    0.0000354641    1      24
16     0.005966652    0.057324466    0.0001393620    1
25     4      0.002979224     0.02862292     0.0002794970    1];
% This program obtains th Bus Admittance Matrix for power flow solution
% Copyright (c) 1998 by H. Saadat
j=sqrt(-1); i = sqrt(-1);
nl = linedata(:,1); nr = linedata(:,2); R = linedata(:,3);
X = linedata(:,4); Bc = j*linedata(:,5); a = linedata(:, 6);
nbr=length(linedata(:,1)); nbus = max(max(nl), max(nr));
Z = R + j*X; y= ones(nbr,1)./Z; %branch admittance
for n = 1:nbr
if a(n) <= 0 a(n) = 1; else end
Ybus=zeros(nbus,nbus); % initialize Ybus to zero
% formation of the off diagonal elements
for k=1:nbr;
Ybus(nl(k),nr(k))=Ybus(nl(k),nr(k))-y(k)/a(k);
Ybus(nr(k),nl(k))=Ybus(nl(k),nr(k));
end
end
% formation of the diagonal elements
for n=1:nbus
for k=1:nbr
if nl(k)==n
Ybus(n,n) = Ybus(n,n)+y(k)/(a(k)^2) + Bc(k);
elseif nr(k)==n
Ybus(n,n) = Ybus(n,n)+y(k) +Bc(k);
else, end
end
end
clear Pgg
% Power flow solution by Newton-Raphson method
% Copyright (c) 1998 by H. Saadat
ns=0; ng=0; Vm=0; delta=0; yload=0; deltad=0;
nbus = length(busdata(:,1));
for k=1:nbus

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n=busdata(k,1);
kb(n)=busdata(k,2); Vm(n)=busdata(k,3); delta(n)=busdata(k,4);
Pd(n)=busdata(k,5); Qd(n)=busdata(k,6); Pg(n)=busdata(k,7); Qg(n) =
busdata(k,8);
Qmin(n)=busdata(k,9); Qmax(n)=busdata(k,10);
Qsh(n)=busdata(k,11);
    if Vm(n) <= 0 Vm(n) = 1.0; V(n) = 1 + j*0;
    else delta(n) = pi/180*delta(n);
        V(n) = Vm(n)*(cos(delta(n)) + j*sin(delta(n)));
        P(n)=(Pg(n)-Pd(n))/basemva;
        Q(n)=(Qg(n)-Qd(n)+ Qsh(n))/basemva;
        S(n) = P(n) + j*Q(n);
    end
end
for k=1:nbus
if kb(k) == 1, ns = ns+1; else, end
if kb(k) == 2 ng = ng+1; else, end
ngs(k) = ng;
nss(k) = ns;
end
Ym=abs(Ybus); t = angle(Ybus);
m=2*nbus-ng-2*ns;
maxerror = 1; converge=1;
iter = 0;
% Start of iterations
clear A DC J DX
while maxerror >= accuracy & iter <= maxiter % Test for max. power
mismatch
for i=1:m
for k=1:m
    A(i,k)=0; %Initializing Jacobian matrix
end, end
iter = iter+1;
for n=1:nbus
nn=n-nss(n);
lm=nbus+n-ngs(n)-nss(n)-ns;
J11=0; J22=0; J33=0; J44=0;
    for i=1:nbr
        if nl(i) == n | nr(i) == n
            if nl(i) == n, l = nr(i); end
            if nr(i) == n, l = nl(i); end
            J11=J11+ Vm(n)*Vm(l)*Ym(n,l)*sin(t(n,l)- delta(n) + delta(l));
            J33=J33+ Vm(n)*Vm(l)*Ym(n,l)*cos(t(n,l)- delta(n) + delta(l));
            if kb(n)~=1
                J22=J22+ Vm(l)*Ym(n,l)*cos(t(n,l)- delta(n) + delta(l));
                J44=J44+ Vm(l)*Ym(n,l)*sin(t(n,l)- delta(n) + delta(l));
            else, end
            if kb(n) ~= 1 & kb(l) ~=1
                lk = nbus+l-ngs(l)-nss(l)-ns;
                ll = l -nss(l);
                % off diagonalelements of J1
                A(nn, ll) =-Vm(n)*Vm(l)*Ym(n,l)*sin(t(n,l)- delta(n) + delta(l));
                if kb(l) == 0 % off diagonal elements of J2
                    A(nn, lk) =Vm(n)*Ym(n,l)*cos(t(n,l)- delta(n) +
delta(l));end
                if kb(n) == 0 % off diagonal elements of J3
                    A(lm, ll) =-Vm(n)*Vm(l)*Ym(n,l)*cos(t(n,l)-
delta(n)+delta(l)); end
                if kb(n) == 0 & kb(l) == 0 % off diagonal elements of J4
                    A(lm, lk) =-Vm(n)*Ym(n,l)*sin(t(n,l)- delta(n) +
delta(l));end

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        else end
    else , end
end
Pk = Vm(n)^2*Ym(n,n)*cos(t(n,n))+J33;
Qk = -Vm(n)^2*Ym(n,n)*sin(t(n,n))-J11;
if kb(n) == 1 P(n)=Pk; Q(n) = Qk; end % Swing bus P
    if kb(n) == 2 Q(n)=Qk;
        if Qmax(n) ~= 0
            Qgc = Q(n)*basemva + Qd(n) - Qsh(n);
            iterations are Vm(n) to within
                if iter <= 7 % Between the 2th & 6th
                    if iter > 2 % the Mvar of generator buses
                        if Qgc < Qmin(n), % tested. If not within limits
                            Vm(n) = Vm(n) + 0.01; % is changed in steps of 0.01 pu
                        elseif Qgc > Qmax(n), % bring the generator Mvar
                            Vm(n) = Vm(n) - 0.01;end % the specified limits.
                        else, end
                    else,end
                else,end
            end
        if kb(n) ~= 1
            A(nn,nn) = J11; %diagonal elements of J1
            DC(nn) = P(n)-Pk;
        end
        if kb(n) == 0
            A(nn,lm) = 2*Vm(n)*Ym(n,n)*cos(t(n,n))+J22; %diagonal elements of
J2
            A(lm,nn)= J33; %diagonal elements of J3
            A(lm,lm) = -2*Vm(n)*Ym(n,n)*sin(t(n,n))-J44; %diagonal of elements
of J4
            DC(lm) = Q(n)-Qk;
        end
    end
DX=A\DC';
for n=1:nbus
    nn=n-nss(n);
    lm=nbus+n-ngs(n)-nss(n)-ns;
    if kb(n) ~= 1
        delta(n) = delta(n)+DX(nn); end
    if kb(n) == 0
        Vm(n)=Vm(n)+DX(lm); end
end
maxerror=max(abs(DC));
    if iter == maxiter & maxerror > accuracy
        fprintf('\nWARNING: Iterative solution did not converged after ')
        fprintf('%g', iter), fprintf(' iterations.\n\n')
        fprintf('Press Enter to terminate the iterations and print the results
\n')
        converge = 0; pause, else, end

end

if converge ~= 1
    tech= (' ITERATIVE SOLUTION DID NOT CONVERGE!');
else,
    tech=(' Power Flow Solution by Newton-Raphson
Method');

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end
V = Vm.*cos(delta)+j*Vm.*sin(delta);
deltad=180/pi*delta;
i=sqrt(-1);
k=0;
for n = 1:nbus
    if kb(n) == 1
        k=k+1;
        S(n)= P(n)+j*Q(n);
        Pg(n) = P(n)*basemva + Pd(n);
        Qg(n) = Q(n)*basemva + Qd(n) - Qsh(n);
        Pgg(k)=Pg(n);
        Qgg(k)=Qg(n);      %june 97
    elseif kb(n) ==2
        k=k+1;
        S(n)=P(n)+j*Q(n);
        Qg(n) = Q(n)*basemva + Qd(n) - Qsh(n);
        Pgg(k)=Pg(n);
        Qgg(k)=Qg(n);    % June 1997
    end
    yload(n) = (Pd(n)- j*Qd(n)+j*Qsh(n))/(basemva*Vm(n)^2);
end
busdata(:,3)=Vm'; busdata(:,4)=deltad';
Pgt = sum(Pg); Qgt = sum(Qg); Pdt = sum(Pd); Qdt = sum(Qd); Qsht =
sum(Qsh);

%clear A DC DX J11 J22 J33 J44 Qk delta lk ll lm
%clear A DC DX J11 J22 J33 Qk delta lk ll lm
% This program prints the power flow solution in a tabulated form
% on the screen.
%
% Copyright (C) 1998 by H. Saadat.

%clc
disp(tech)
fprintf('                Maximum Power Mismatch = %g \n', maxerror)
fprintf('                No. of Iterations = %g \n\n', iter)
head =['   Bus   Voltage   Angle   -----Load-----   ---Generation---
Injected'
       '   No.   Mag.     Degree     MW         Mvar         MW         Mvar
Mvar '
       '
'];
disp(head)
for n=1:nbus
    fprintf(' %5g', n), fprintf(' %7.3f', Vm(n)),
    fprintf(' %8.3f', deltad(n)), fprintf(' %9.3f', Pd(n)),
    fprintf(' %9.3f', Qd(n)), fprintf(' %9.3f', Pg(n)),
    fprintf(' %9.3f ', Qg(n)), fprintf(' %8.3f\n', Qsh(n))
end
fprintf('          \n'), fprintf('      Total          ')
fprintf(' %9.3f', Pdt), fprintf(' %9.3f', Qdt),
fprintf(' %9.3f', Pgt), fprintf(' %9.3f', Qgt), fprintf(' %9.3f\n\n',
Qsht)
% This program is used in conjunction with lfgauss or lf Newton
% for the computation of line flow and line losses.
%
% Copyright (c) 1998 H. Saadat
SLT = 0;
fprintf('\n')
fprintf('                Line Flow and Losses \n\n')

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```

fprintf('    --Line--  Power at bus & line flow    --Line loss--
Transformer\n')
fprintf('    from to    MW        Mvar        MVA        MW        Mvar
tap\n')

for n = 1:nbus
busprt = 0;
    for L = 1:nbr;
        if busprt == 0
            fprintf('    \n'), fprintf('%6g', n), fprintf('    %9.3f',
P(n)*basemva)
            fprintf('%9.3f', Q(n)*basemva), fprintf('%9.3f\n',
abs(S(n)*basemva))

            busprt = 1;
        else, end
        if nl(L)==n        k = nr(L);
In = (V(n) - a(L)*V(k))*y(L)/a(L)^2 + Bc(L)/a(L)^2*V(n);
Ik = (V(k) - V(n)/a(L))*y(L) + Bc(L)*V(k);
Snk = V(n)*conj(In)*basemva;
Skn = V(k)*conj(Ik)*basemva;
SL  = Snk + Skn;
SLT = SLT + SL;
        elseif nr(L)==n    k = nl(L);
In = (V(n) - V(k)/a(L))*y(L) + Bc(L)*V(n);
Ik = (V(k) - a(L)*V(n))*y(L)/a(L)^2 + Bc(L)/a(L)^2*V(k);
Snk = V(n)*conj(In)*basemva;
Skn = V(k)*conj(Ik)*basemva;
SL  = Snk + Skn;
SLT = SLT + SL;
        else, end
            if nl(L)==n | nr(L)==n
                fprintf('%12g', k),
                fprintf('%9.3f', real(Snk)), fprintf('%9.3f', imag(Snk))
                fprintf('%9.3f', abs(Snk)),
                fprintf('%9.3f', real(SL)),
                    if nl(L) ==n & a(L) ~= 1
                        fprintf('%9.3f', imag(SL)), fprintf('%9.3f\n', a(L))
                    else, fprintf('%9.3f\n', imag(SL))
                    end
                end
            else, end
        end
    end
SLT = SLT/2;
fprintf('    \n'), fprintf('    Total loss    ')
fprintf('%9.3f', real(SLT)), fprintf('%9.3f\n', imag(SLT))
clear Ik In SL SLT Skn Snk

```

Lampiran 3 Listing Program Aliran Daya Pada Sistem JAMALI 500kV Setelah Penempatan STATCOM Dengan Optimasi BFO

```

clear;
clc;
format long
tic
basemva = 1000; accuracy = 10^-4; accel = 1.8; maxiter = 1000;
% Bus Data jamali 500kV
% Line Data JAMALI 500 kV

```



```

% Bacterial Foraging Optimization
Nvar =3;      % Jumlah STATCOM
NBac = 20;    % Number of bacteria in the colony
NChem = 10;   % Number of chemotactic steps
NSwim = 4;    % Number of swim steps
NRep = 10;    % Number of reproductive steps
NEDi = 10;    % Number of elimination and dispersal steps
Sr = NBac/2;  % The number of bacteria reproductions (splits) per
generation
PEDi = 0.5;   % The probability that each bacteria will be
eliminated/dispersed
RLeng(:,1)=25*ones(NBac,1); % the run length unit (the size of the step
taken in each run or tumble)
Rb1 = 1;      % Batas bawah interval Lokasi
Ra1 = max(busdata(:,1)); % Batas akhir interval Lokasi
Rb2 =-450;    % Batas bawah interval MVAR
Ra2 =600;    % Batas atas interval MVAR

% the initital posistions
for nn = 1 : NBac
    X1(:,nn,1,1,1) = randperm(Ra1,Nvar);
    X2(:, :,1,1,1) = ((rand(NBac,Nvar)*(Ra2-Rb2))+Rb2)';
end

for l11 = 1:NEDi
    % (3) Reproduction loop
    for kkk = 1:NRep
        % (4) Chemotaxis (swim/tumble) loop
        for jjj = 1:NChem
            % (4.1) Chemotatic step
            for iii = 1:NBac
                % (4.2) Fitness function
                Fit(iii,jjj,kkk,l11) =
EvaluasiIndividu(busdata,linedata,X1(:,iii,jjj,kkk,l11),X2(:,iii,jjj,kkk,
l11),Nvar);
                % (4.3) Jlast
                Fitlast=Fit(iii,jjj,kkk,l11);
                % (4.4) Tumble
                Delta(:,iii) = unifrnd(-1,1,Nvar,1);
                % (4.5) Move
                X1(:,iii,jjj+1,kkk,l11)= randperm(Ra1,Nvar);
                X2(:,iii,jjj+1,kkk,l11)=
X2(:,iii,jjj,kkk,l11)+RLeng(iii,kkk)*Delta(:,iii)/sqrt(Delta(:,iii)'+Delt
a(:,iii));
                for chck=1:Nvar
                    if X2(chck,iii,jjj+1,kkk,l11) > Ra2
                        X2(chck,iii,jjj+1,kkk,l11) = Ra2;
                    elseif X2(chck,iii,jjj+1,kkk,l11) < Rb2
                        X2(chck,iii,jjj+1,kkk,l11) = Rb2;
                    end
                end
                % (4.6) New fitness function
                Fit(iii,jjj+1,kkk,l11) =
EvaluasiIndividu(busdata,linedata,X1(:,iii,jjj+1,kkk,l11),X2(:,iii,jjj+1,
kkk,l11),Nvar);
                % (4.7) Swimming
                m=0; % counter for swim length
                while m < NSwim
                    m = m + 1;
                    if Fit(iii,jjj+1,kkk,l11)> Fitlast
                        Fitlast = Fit(iii,jjj+1,kkk,l11);
                    end
                end
            end
        end
    end
end

```

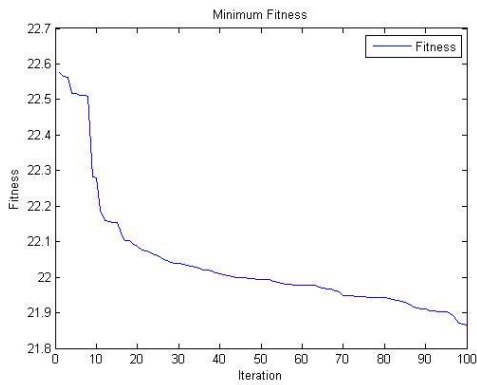
```

X1(:,iii,jjj+1,kkk,111) = randperm(Ra1,Nvar);
X2(:,iii,jjj+1,kkk,111) =
X2(:,iii,jjj+1,kkk,111)+RLeng(iii,kkk)*Delta(:,iii)/sqrt(Delta(:,iii)'*De
lta(:,iii));
    for chck=1:Nvar
        if X2(chck,iii,jjj+1,kkk,111) > Ra2
            X2(chck,iii,jjj+1,kkk,111) = Ra2;
        elseif X2(chck,iii,jjj+1,kkk,111) < Rb2
            X2(chck,iii,jjj+1,kkk,111) = Rb2;
        end
    end
    Fit(iii,jjj+1,kkk,111) =
EvaluasiIndividu(busdata,linedata,X1(:,iii,jjj+1,kkk,111),X2(:,iii,jjj+1,
kkk,111),Nvar);
    else
        m = NSwim;
    end
end
Fit(iii,jjj,kkk,111) = Fitlast;
end % (4.8) Next bacterium
end % (5) if j < Nc, chemotaxis
% (6) Reproduction
% (6.1) Health
Fithealth = sum(Fit(:, :, kkk, 111), 2); % Set the health of
each of the S bacteria
[Fithealth, sortind] = sort(Fithealth, 'descend'); % Sorts bacteria
in order of descending values
X1(:, :, 1, kkk+1, 111) = X1(:, sortind, NChem+1, kkk, 111);
X2(:, :, 1, kkk+1, 111) = X2(:, sortind, NChem+1, kkk, 111);
RLeng(:, kkk+1) = RLeng(sortind, kkk); % Keeps the
chemotaxis parameters with each bacterium at the next generation
% (6.2) Split the bacteria
for spl=1:Sr % Sr??
    X1(:, spl+Sr, 1, kkk+1, 111) = X1(:, spl, 1, kkk+1, 111); % The
least fit do not reproduce, the most fit ones split into two identical
copies
    X2(:, spl+Sr, 1, kkk+1, 111) = X2(:, spl, 1, kkk+1, 111);
    RLeng(spl+Sr, kkk+1) = RLeng(spl, kkk+1);
end
end % (7) Loop to go to the next reproductive step
% (8) Elimination-dispersal
for mmm = 1:NBac
    if PEDI>rand % % Generate random number
        X1(:, mmm, 1, 1, 111+1) = randperm(Ra1, Nvar);
        X2(:, mmm, 1, 1, 111+1) = ((rand(1, Nvar) * (Ra2 - Rb2)) + Rb2)';
    else
        X1(:, mmm, 1, 1, 111+1) = X1(:, mmm, 1, NRep+1, 111); % Bacteria that
are not dispersed
        X2(:, mmm, 1, 1, 111+1) = X2(:, mmm, 1, NRep+1, 111);
    end
end
end
en

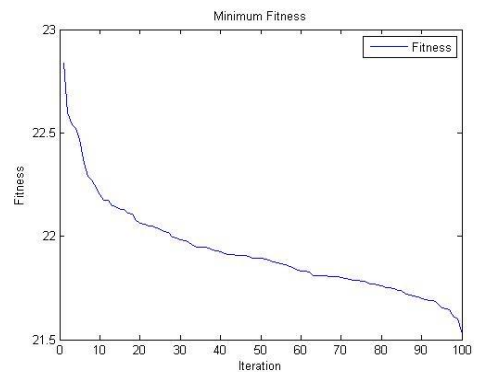
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Lampiran 4 Hasil Pengujian

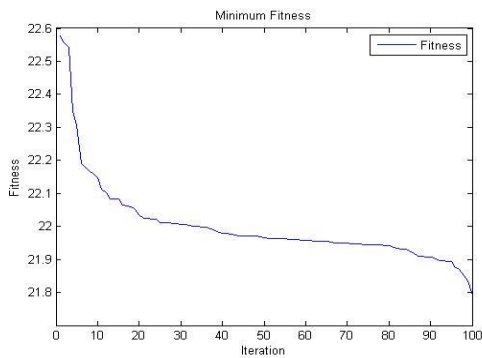
Data IEEE 30 Bus dengan Kapasitor Bank



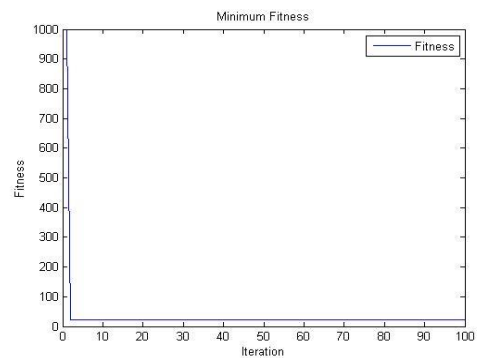
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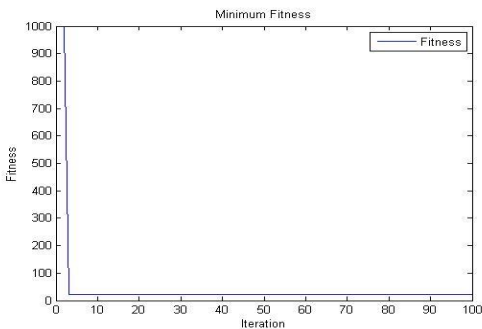
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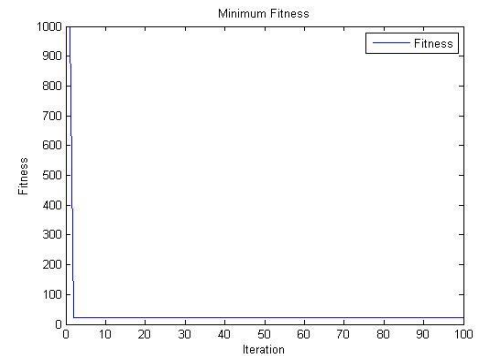
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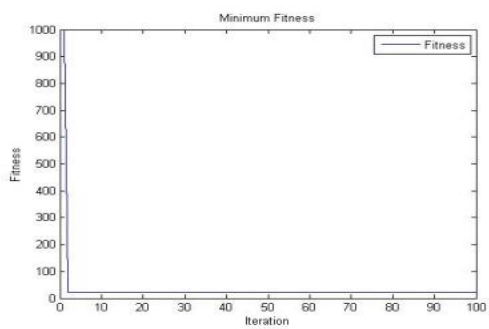
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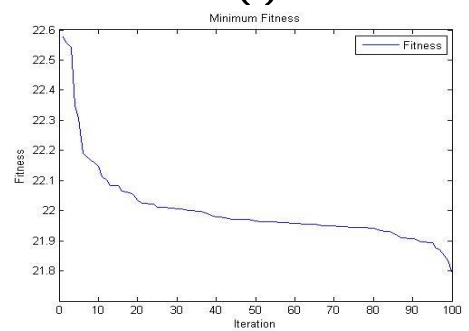
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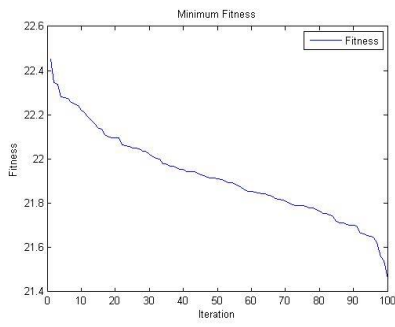
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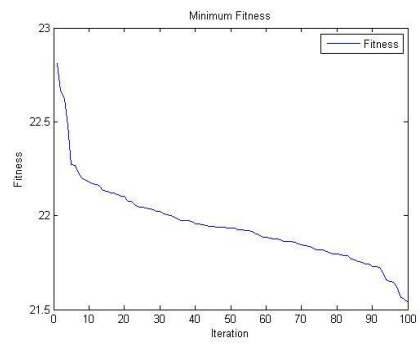
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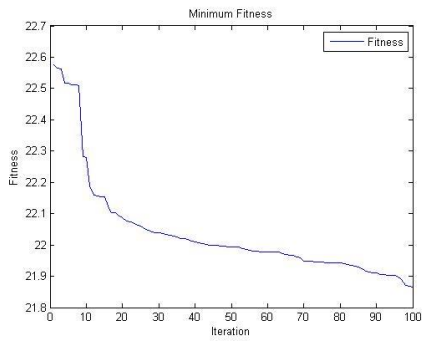


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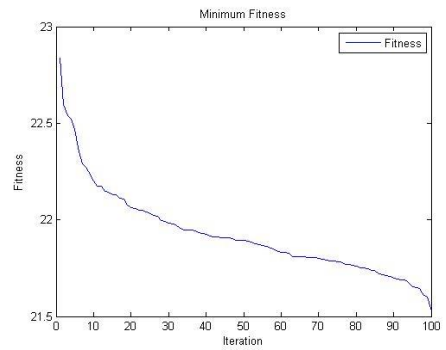


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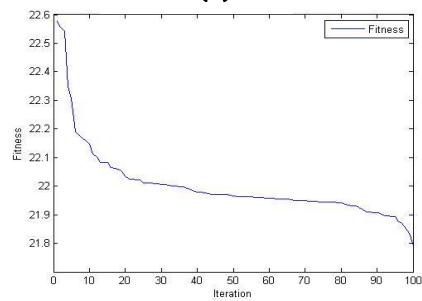
Data IEEE 30 Bus dengan STATCOM



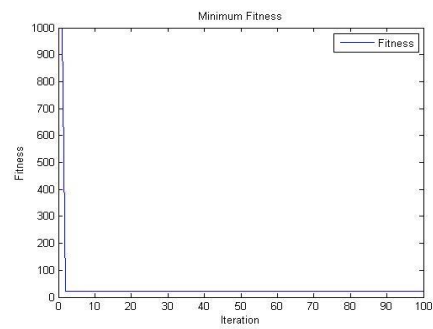
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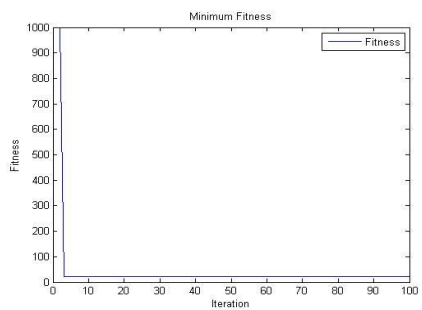
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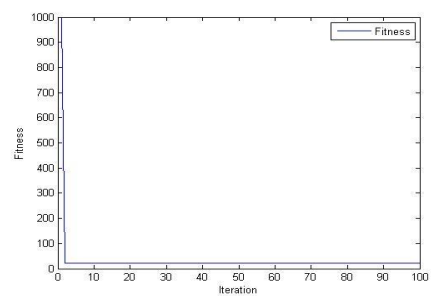
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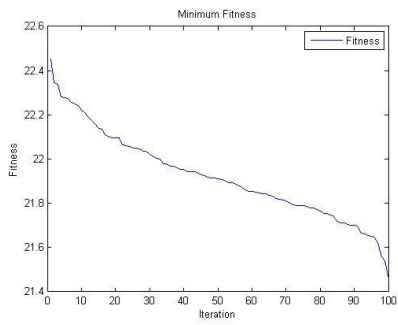
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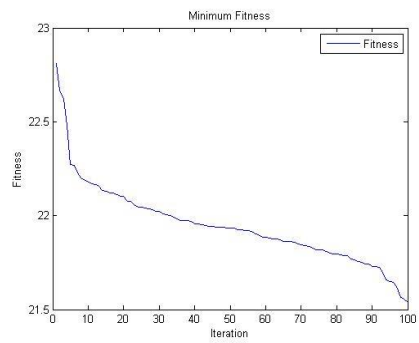
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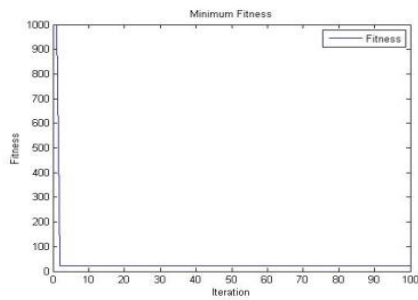
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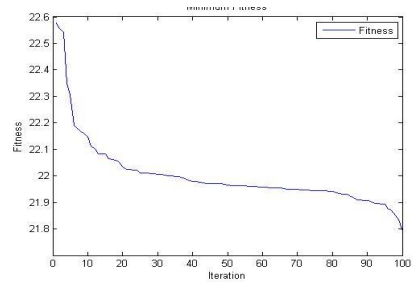
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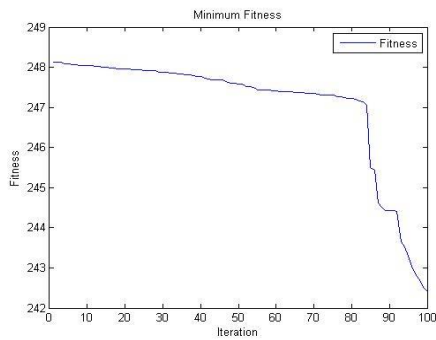


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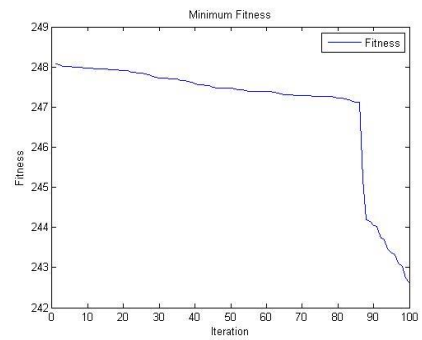


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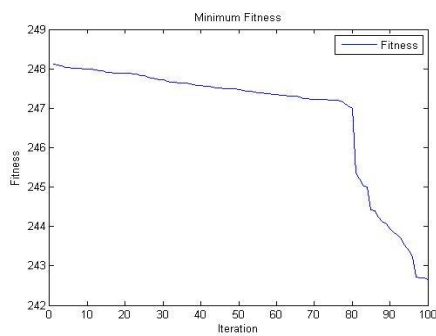
Data JAMALI 500 kV Bus dengan kapasitor bank



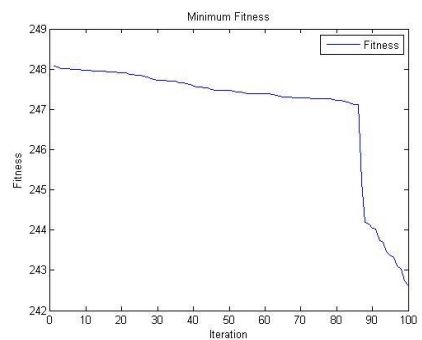
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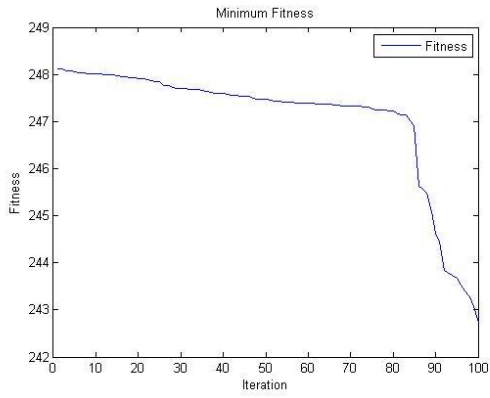
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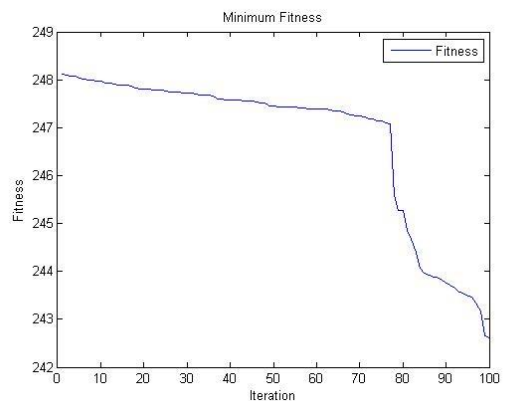
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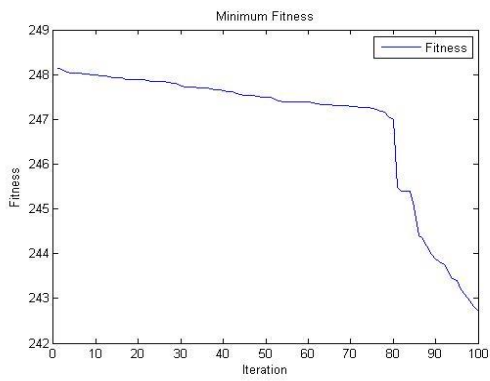
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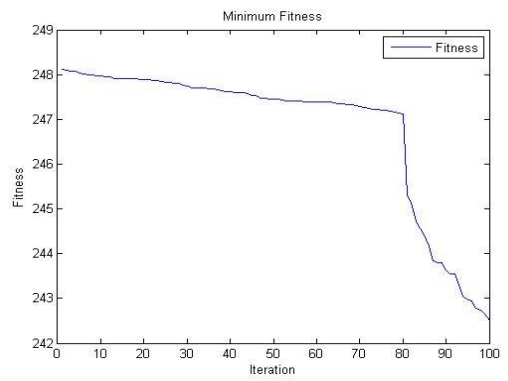
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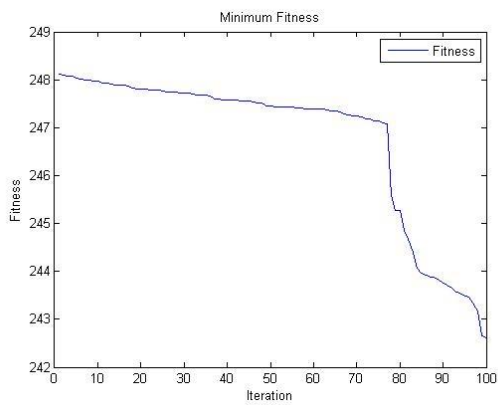
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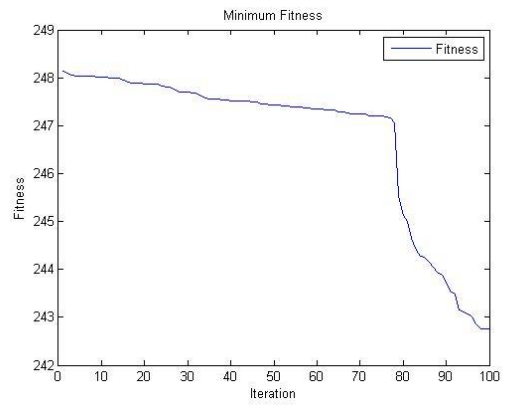
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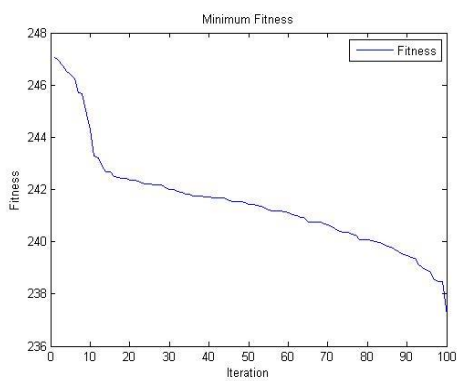


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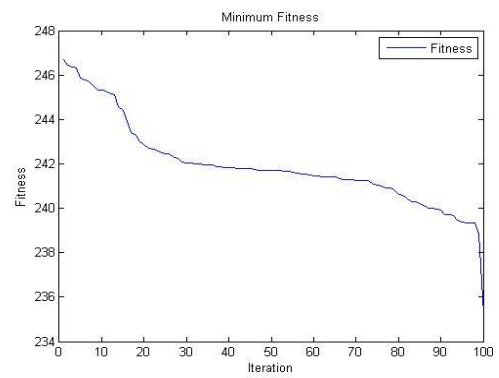


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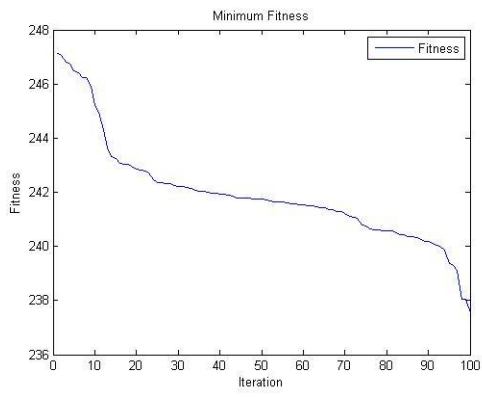
Data JAMALI 500 kV Bus dengan STATCOM



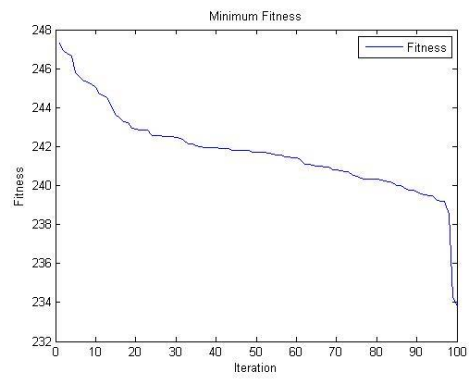
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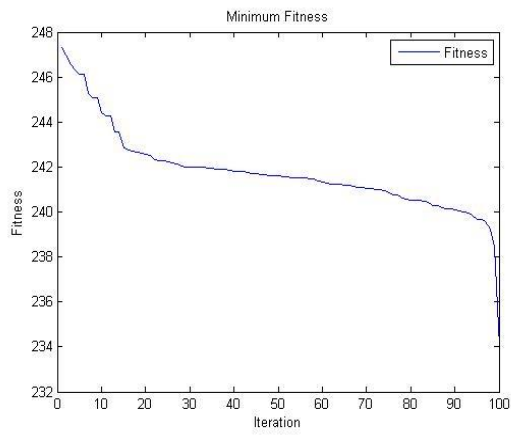
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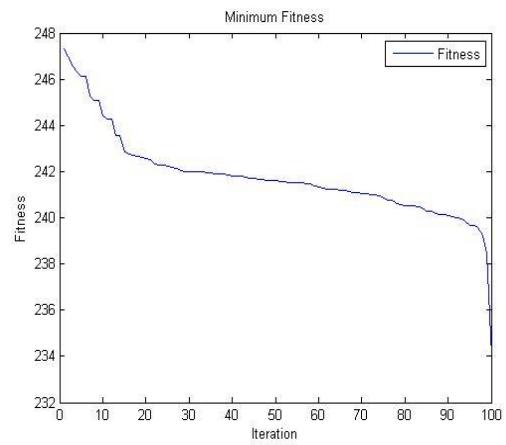
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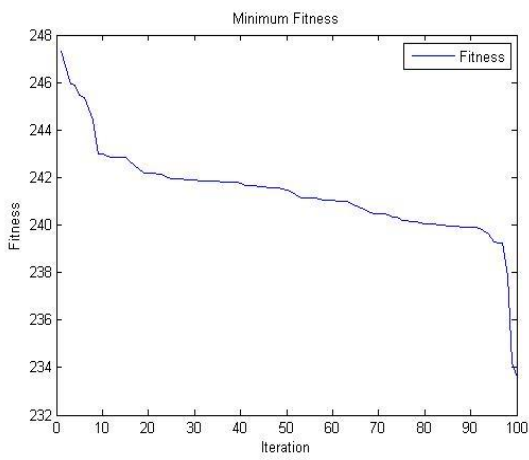
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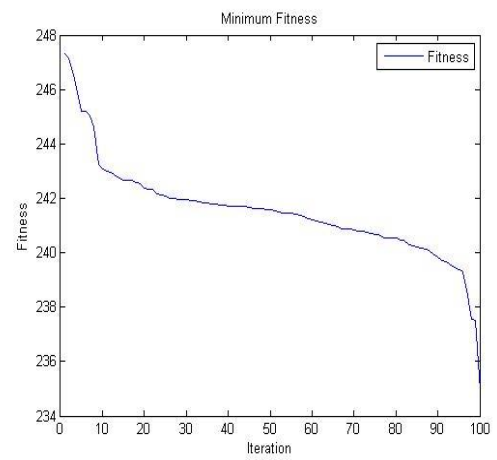
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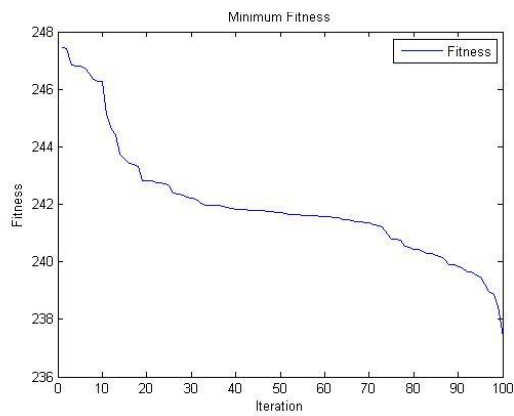
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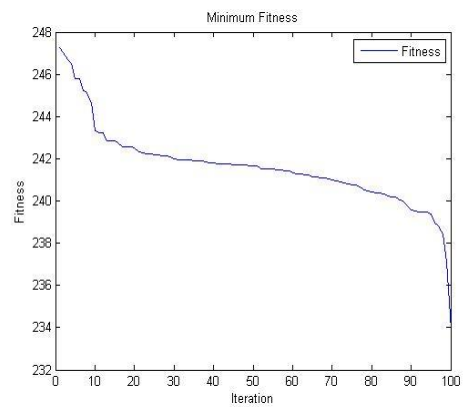
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(8)



(9)



(10)